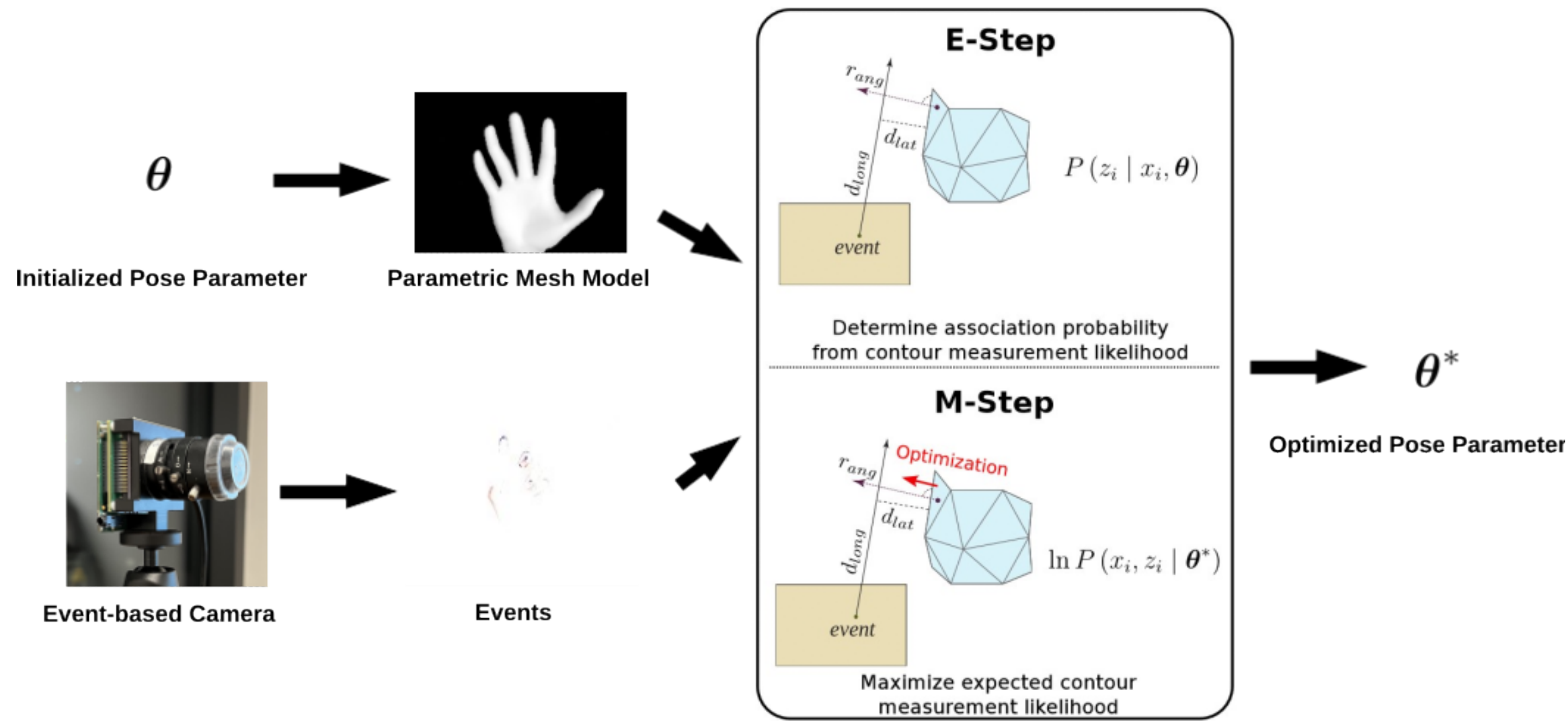


We propose a novel approach for **reconstructing fast non-rigid object deformations** using measurements from **event-based cameras**.

We observe that the majority of events of texture-less object motions are generated at the object **contour**. Our approach estimates the deformation of objects from **events generated at the object contour** in a **probabilistic optimization framework**.

Compared to baseline approaches, our method outperforms them in non-rigid reconstruction quantitatively and qualitatively.

## Event-based Non-Rigid Reconstruction



E-step: Determine association probability based on latest MANO[6] pose parameter.

$$p(z_i = j | x_i, \theta) = \frac{p(x_i | z_i = j, \theta)p(z_i = j | \theta)}{\sum_{j'} p(x_i | z_i = j', \theta)p(z_i = j' | \theta)} = \frac{p(x_i | z_i = j, \theta)}{\sum_{j'} p(x_i | z_i = j', \theta)}$$

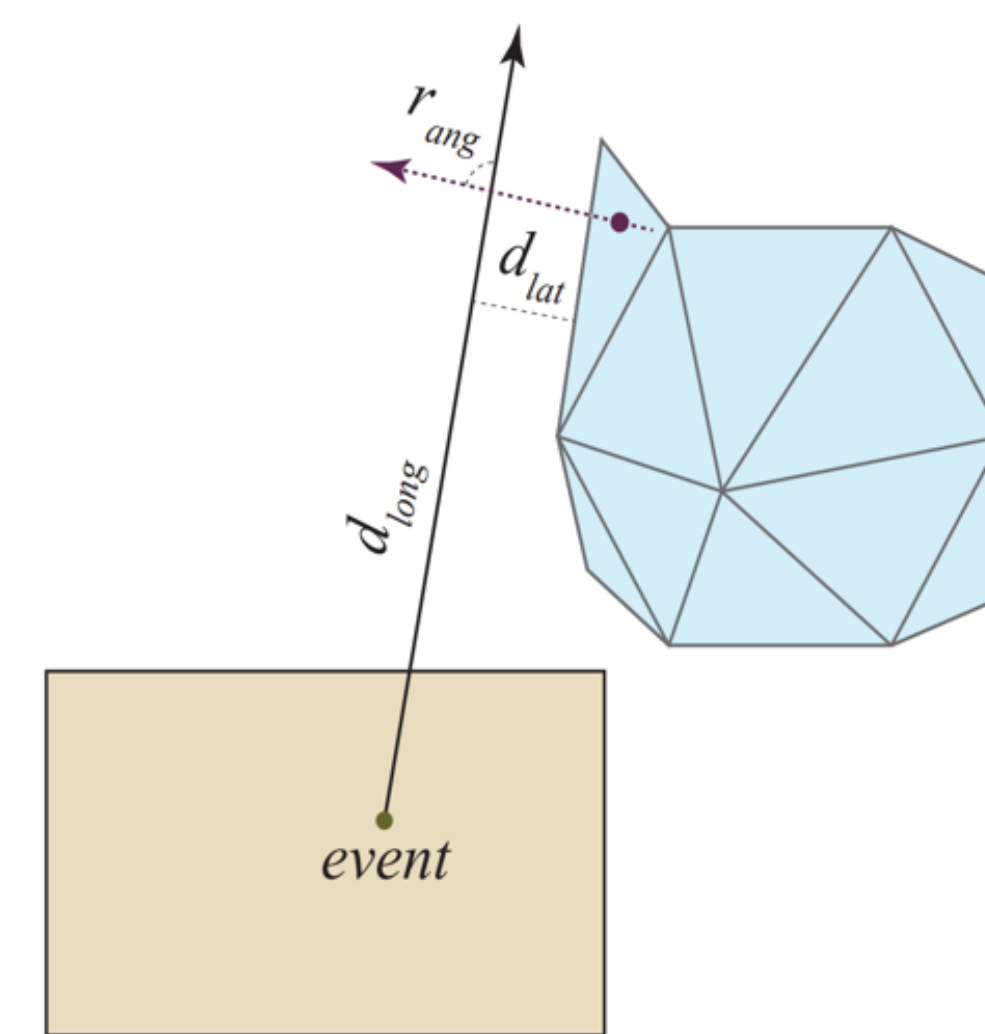
M-step: Maximize the expected contour measurement likelihood to update pose parameter.

$$p(x_i, z_i = j | \theta) = p(x_i | z_i = j, \theta)p(z_i = j | \theta) \propto p(x_i | z_i = j, \theta)$$

Iteration: optimize pose parameter by alternating E- and M-step.

## Measurement Likelihood

We use the measurement likelihood in E-step (to calculate the association likelihood) and M-step.



We formulate the measurement likelihood that an event  $x_i$  is caused by a mesh face  $f_j$  using

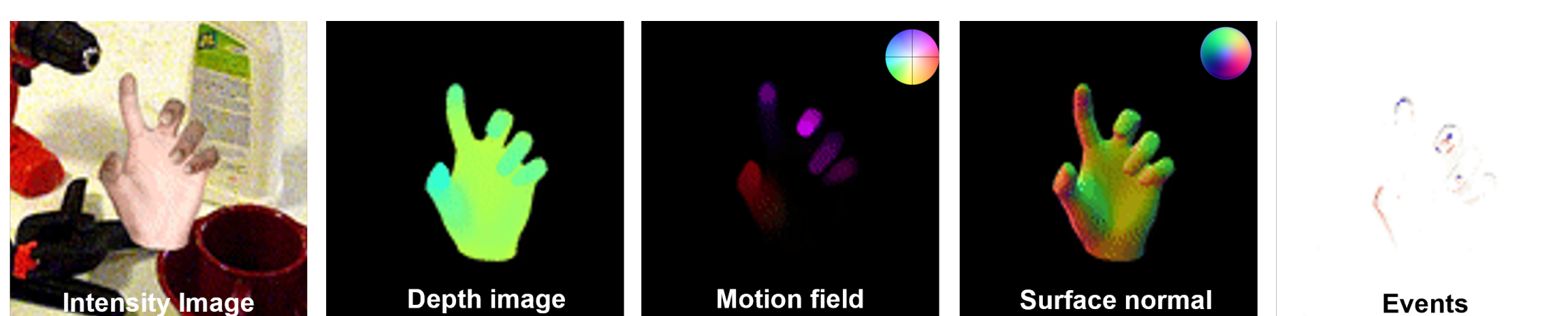
- lateral distance  $d_{lat}$
- longitudinal distance  $d_{long}$  (not used in M-step)
- angular error  $r_{ang}$  between the line of sight through event  $x_i$  and the mesh face  $f_j$ .

We formulate the measurement likelihood on the observed contour as

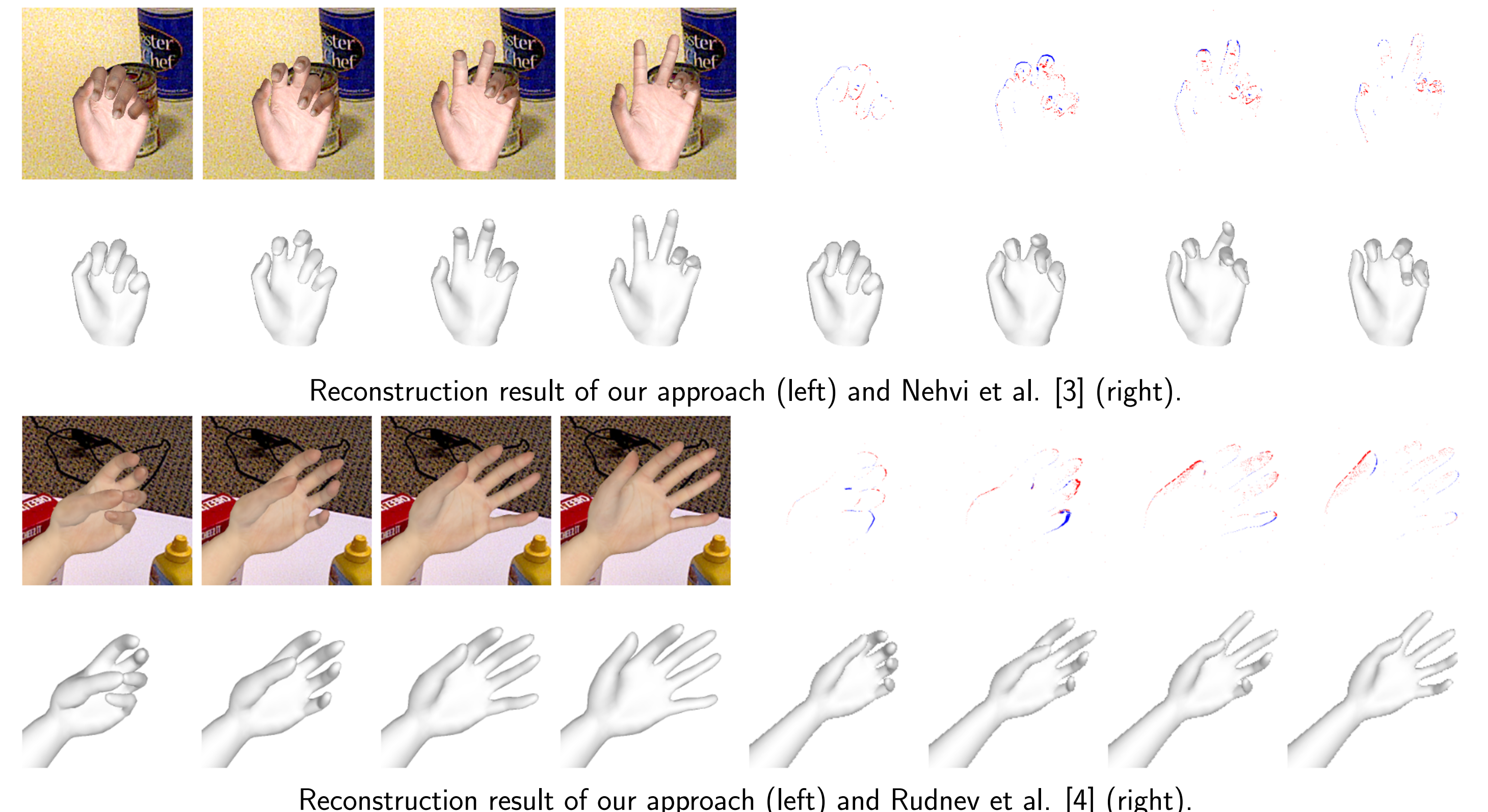
$$p(x_i | z_i = j, \theta) \propto \underbrace{\sigma \left( \delta_j^i \frac{d_{lat}^2(i, j)}{\alpha} \right)}_{lateral} \underbrace{\exp \left( -\frac{d_{long}(i, j)}{\beta} \right)}_{longitudinal} \underbrace{\exp \left( -\frac{r_{ang}(i, j)}{\gamma} \right)}_{contour}$$

## Event Stream Simulator

Inspired by state-of-the-art works, we propose our event stream simulator which supports **more data modalities** and **parametric body models**.

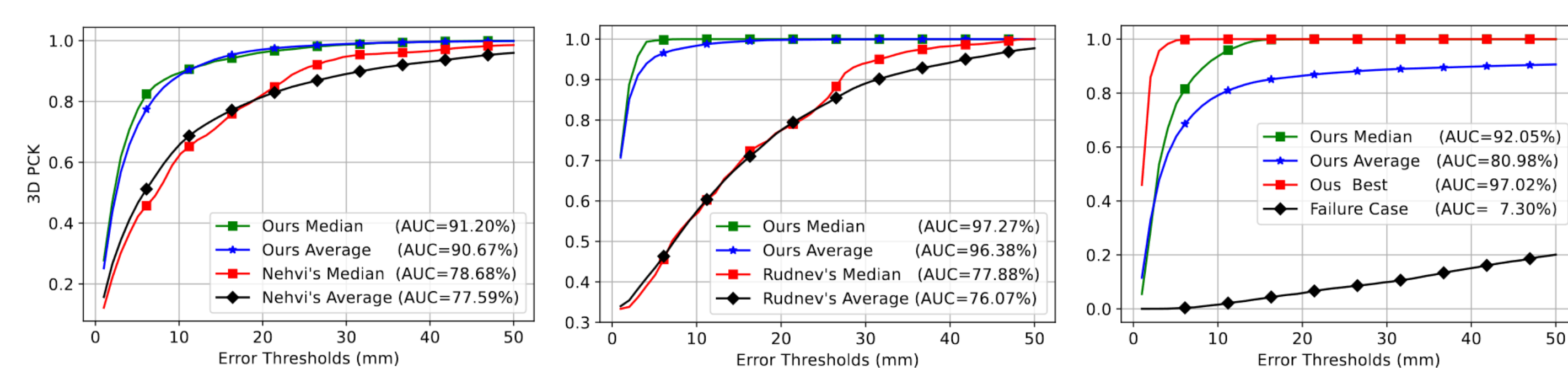


## Results on Synthetic Data



## Quantitative Results on Synthetic Data

Scenario	Method	Mean MPJPE (mm)	Median MPJPE (mm)
MANO hand	Nehvi et al. [3]	11.61	10.85
	<b>Ours</b>	<b>4.52</b>	<b>4.27</b>
SMPL-X hand	Rudnev et al. [4]	11.88	10.73
	<b>Ours</b>	<b>1.11</b>	<b>0.76</b>
SMPL-X arm & hand	<b>Ours</b>	<b>15.39</b>	<b>3.93</b>



Results on MANO [6] (left), SMPL-X [2] hand (middle), and SMPL-X [2] arm & hand (right) scenario.

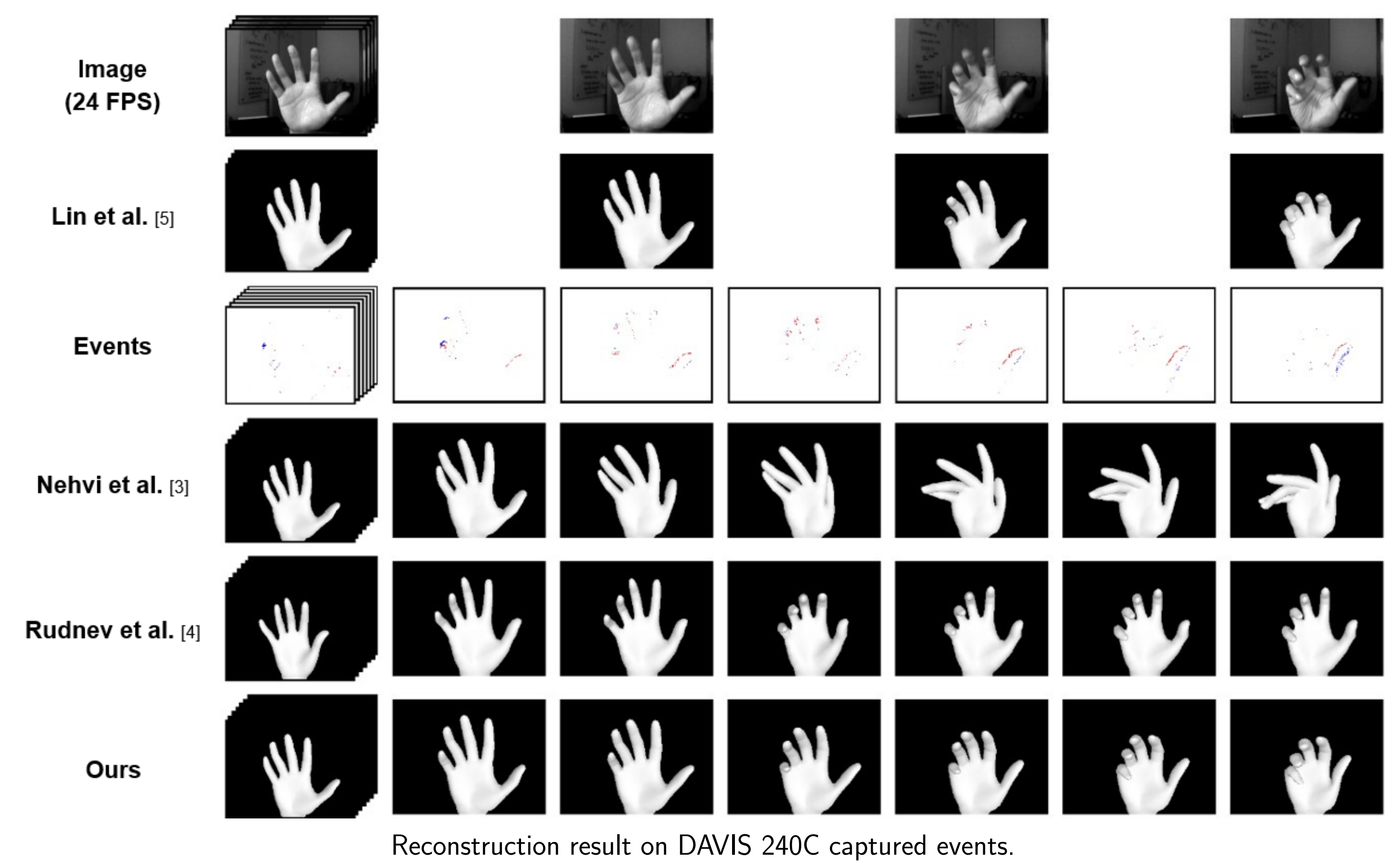
## Conclusion & Outlook

**Contribution:** propose the definition of **contour events**; an **EM-based non-rigid reconstruction** approach from contour events; an **efficient multi-modal event stream simulator**

**Limitation:** ill-constrained settings, e.g. not enough contour events; not real-time capable yet.

**Future Works:** combine events and intensity frames to recover global rigid transformation; assign event to smaller range of mesh face and use parallel programming to increase efficiency

## Results on Real Data



Reconstruction result on DAVIS 240C captured events.

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